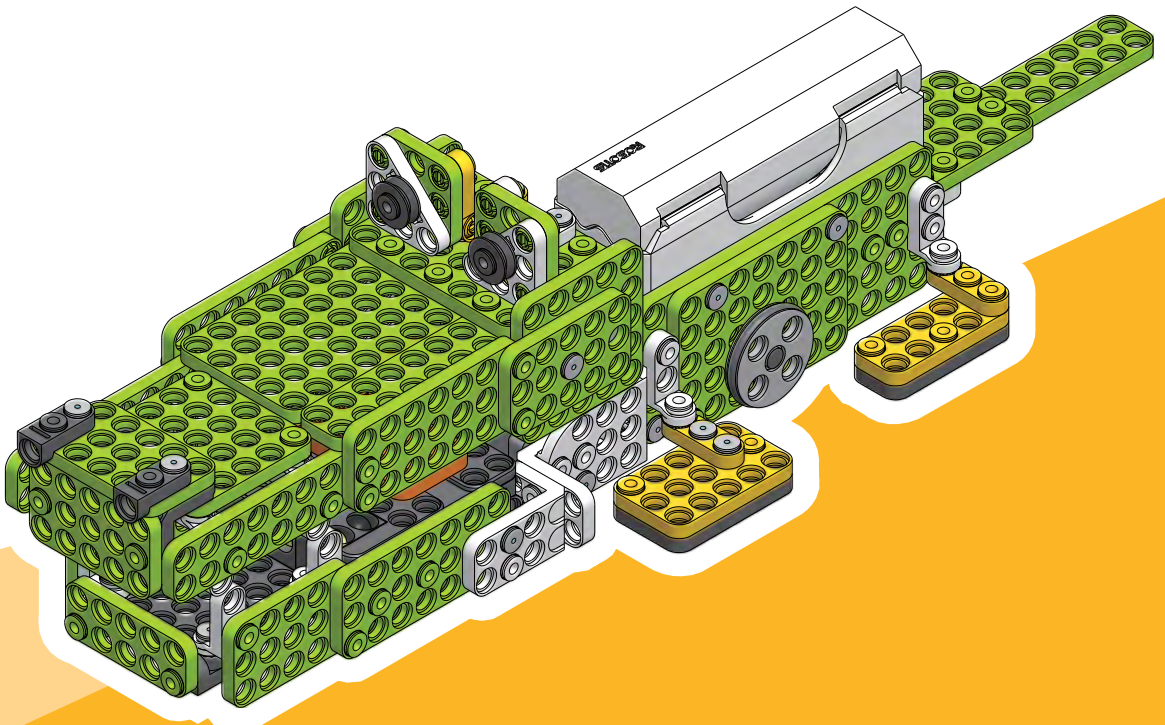


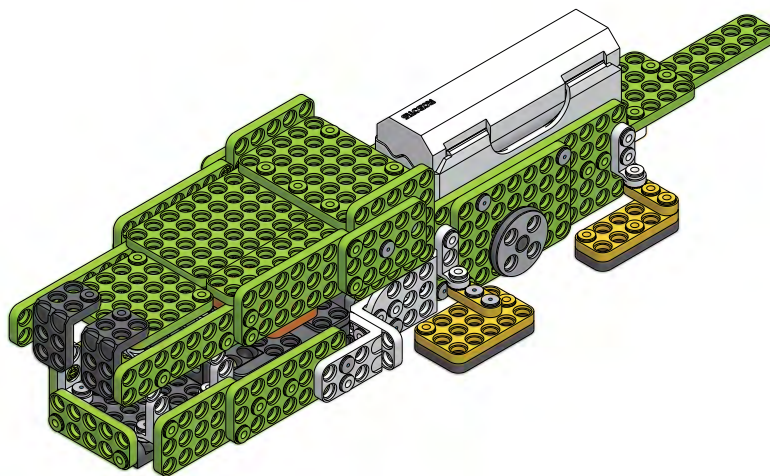


# Crocodile

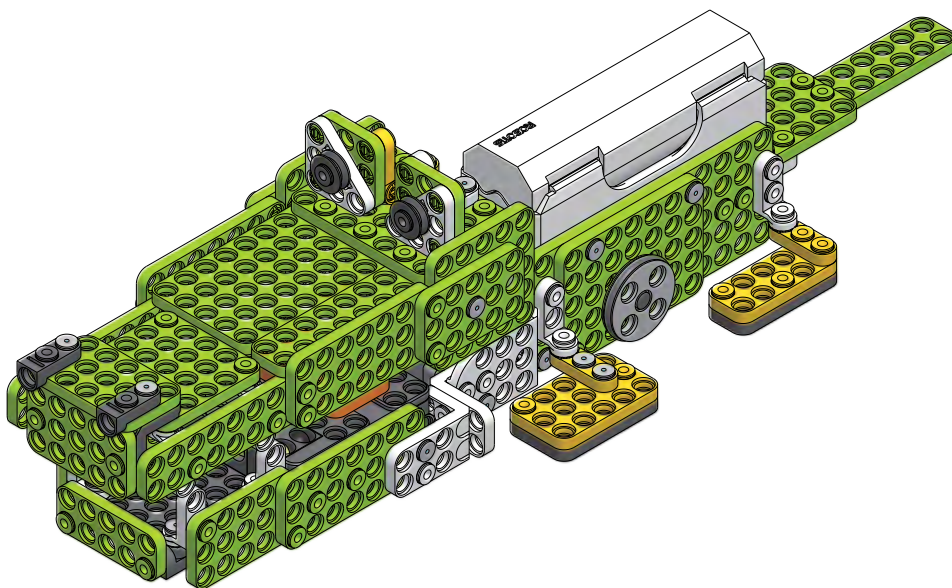


## Let's build!

Let's build a robot.



Below is the final image of the robot when you are done with assembling the “My Own Robot” step.

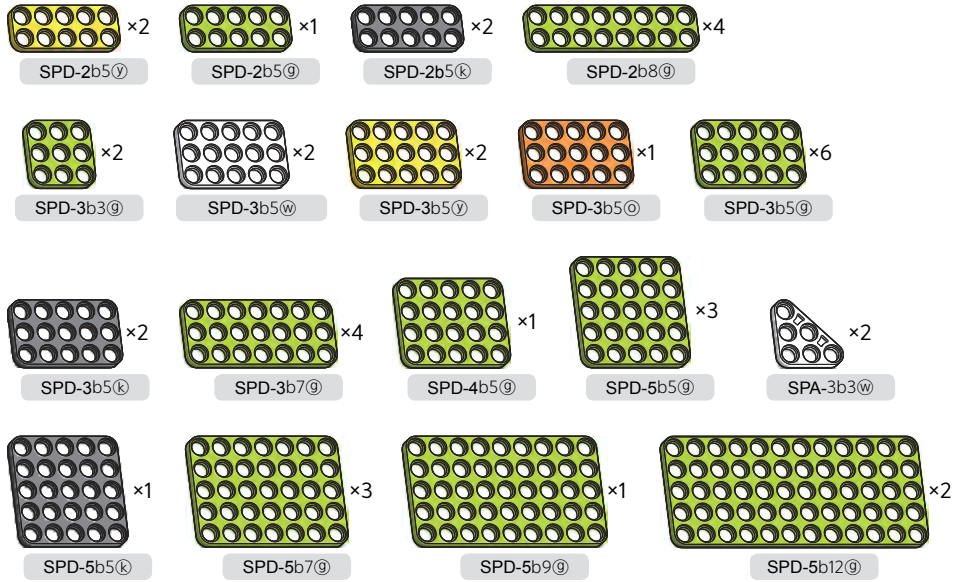


You will require the following parts.

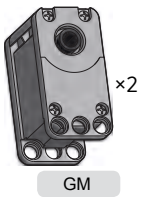
**Rivet**



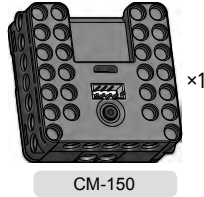
**Plate**



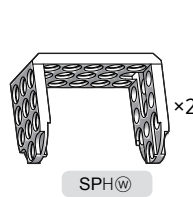
**Geared motor**



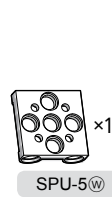
**Controller**



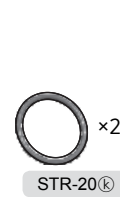
**Hinge**



**Adaptor**



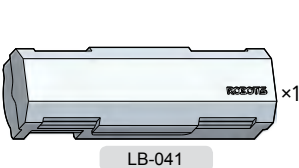
**Tire**



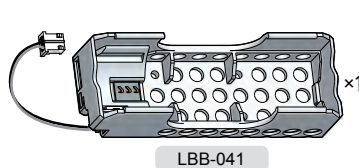
**Spindle**



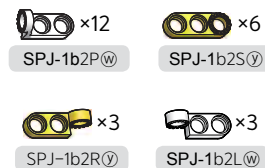
**Battery**



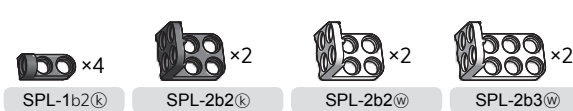
**Battery box**



**Joint**



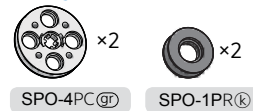
**Bracket**



**Cross horn**



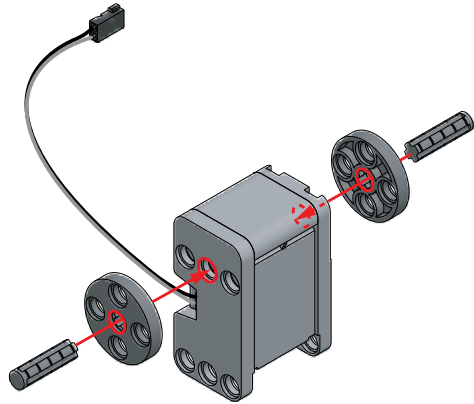
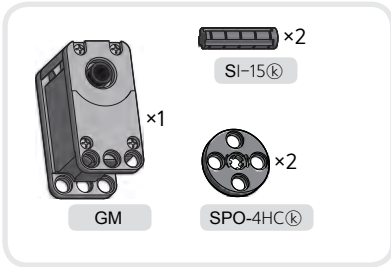
**Pulley**



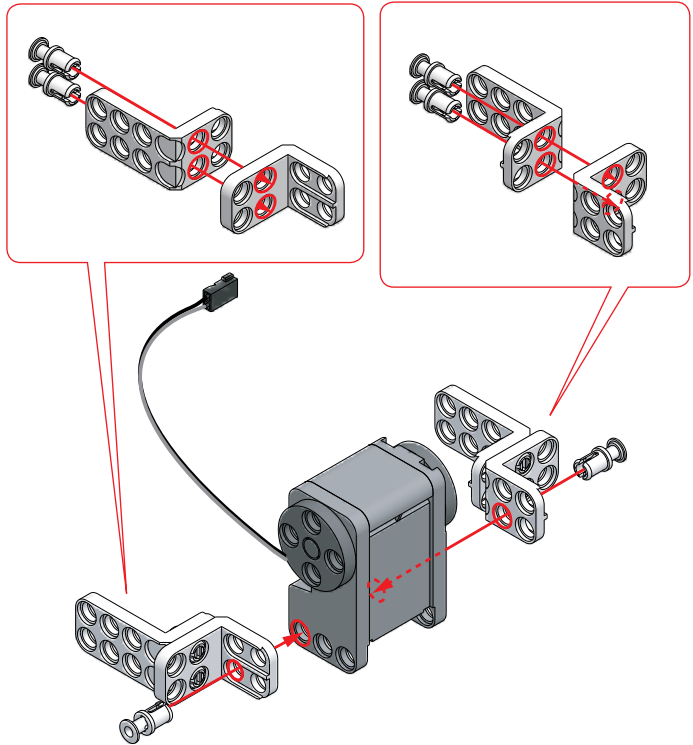
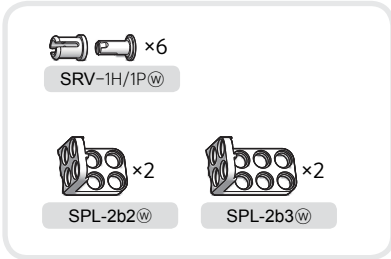
• Parts and color of the products might be different from the images of the assembly manual.

## Building a Crocodile Robot.

1



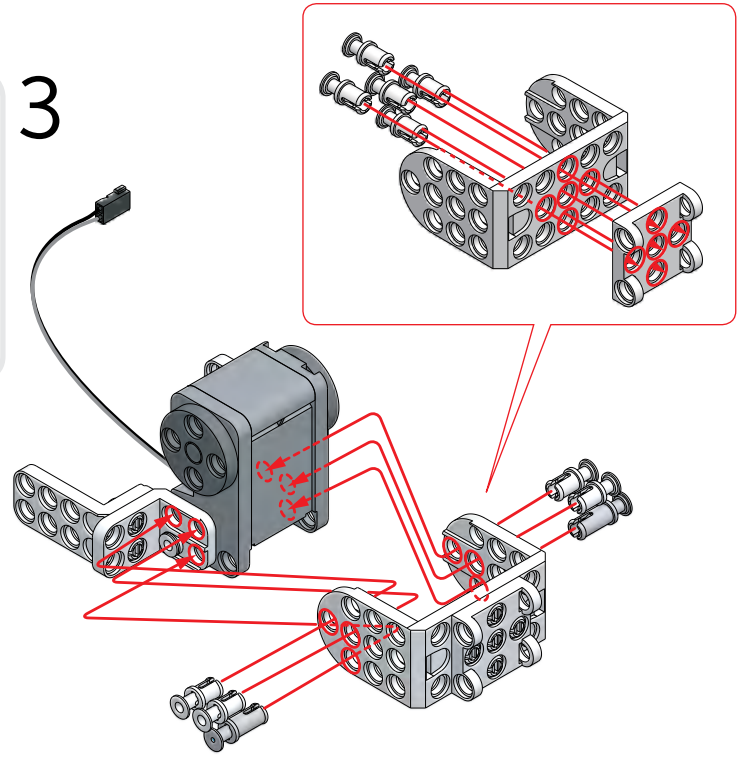
2





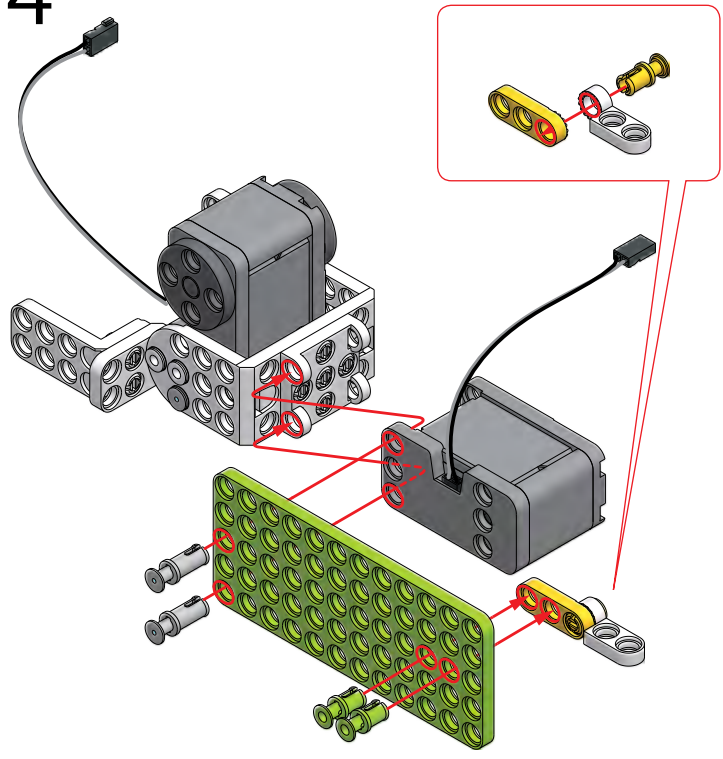
- ×9
- ×2
- ×1
- ×1

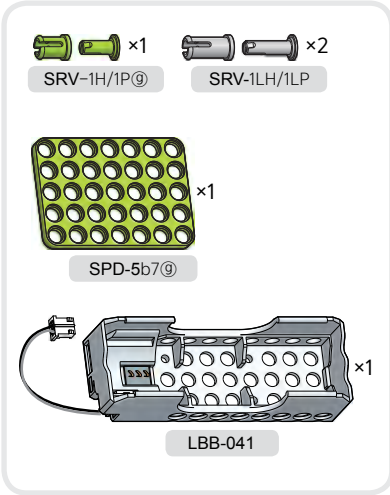
### 3



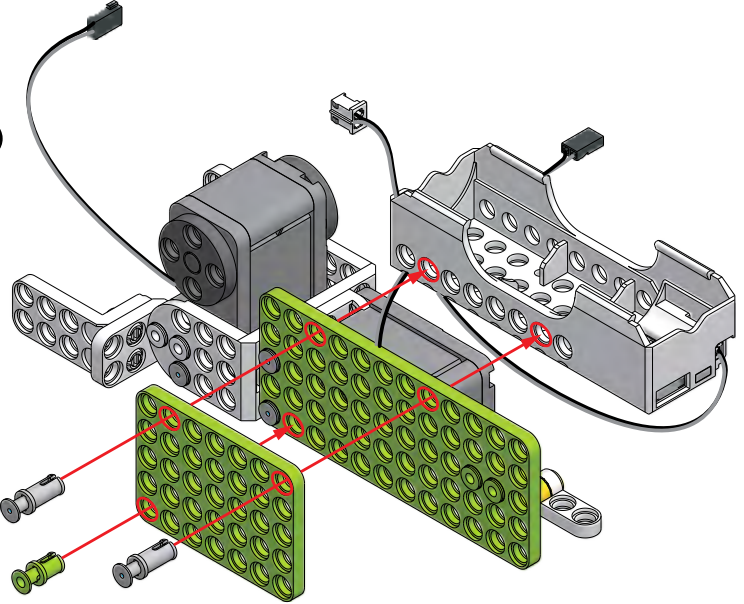
- ×1
- ×2
- ×2
- ×1
- ×1
- ×1
- ×1

### 4

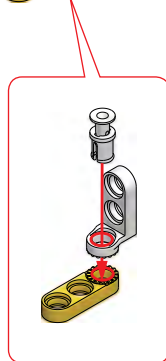
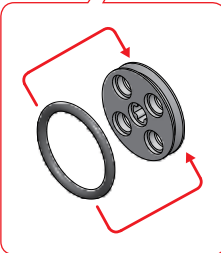
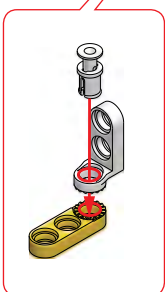
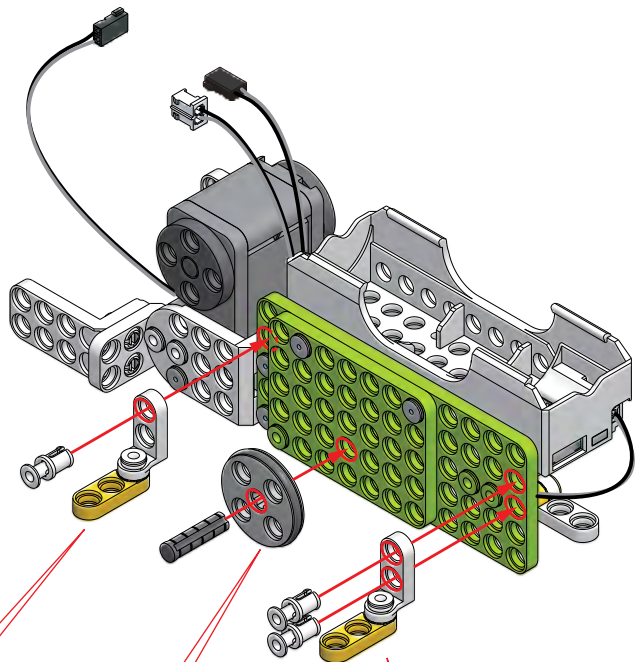




5

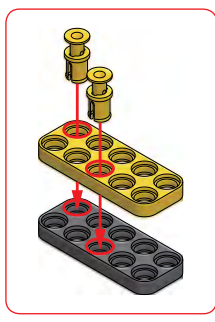
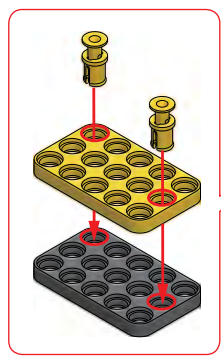
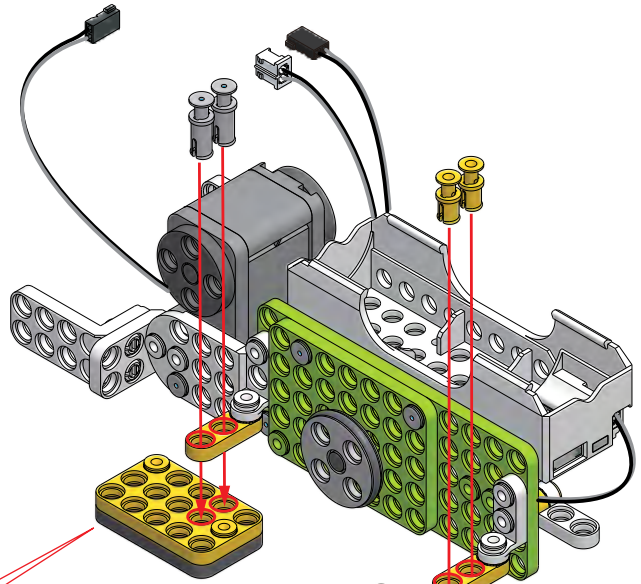


6






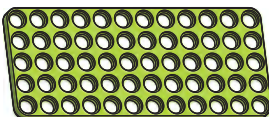


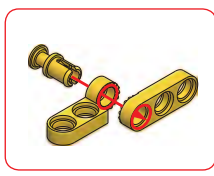
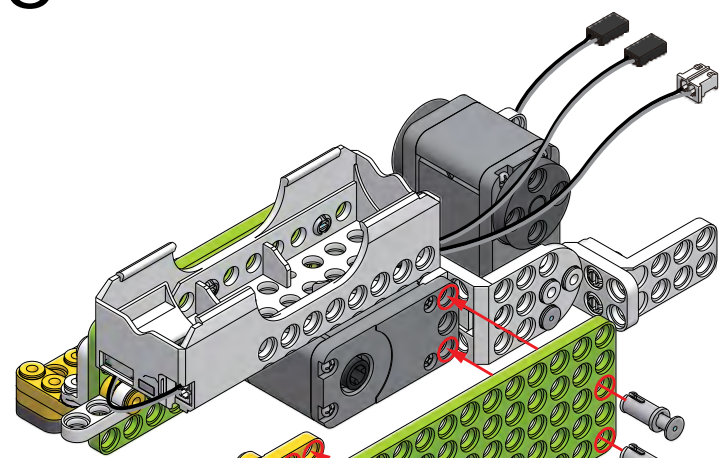
# 7

-  ×6  
SRV-1H/1P (V)
-  ×2  
SRV-1LH/1LP
-  ×1  
SPD-2b5 (V)
-  ×1  
SPD-2b5 (K)
-  ×1  
SPD-3b5 (V)
-  ×1  
SPD-3b5 (K)

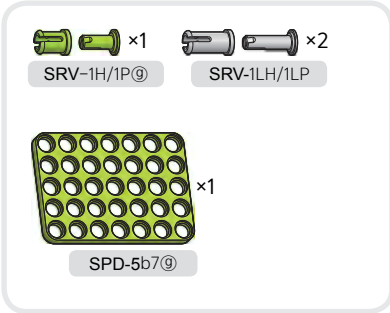


# 8

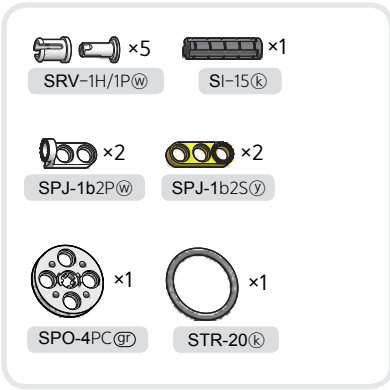
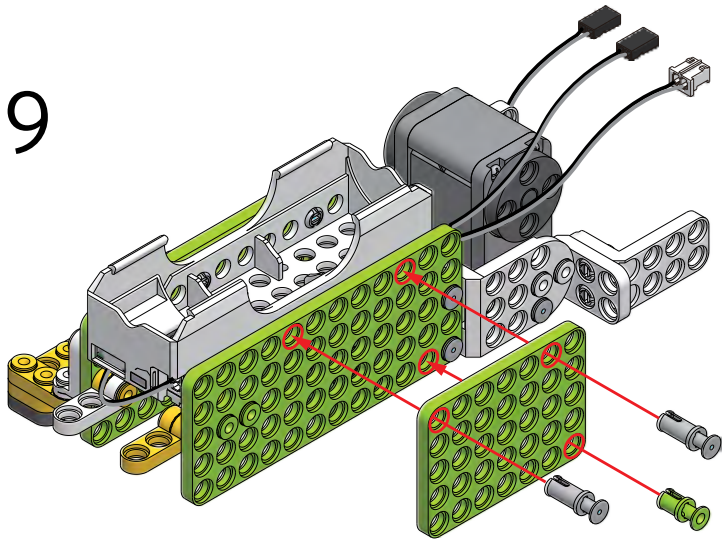
-  ×1  
SRV-1H/1P (V)
-  ×2  
SRV-1H/1P (G)
-  ×2  
SRV-1LH/1LP
-  ×1  
SPJ-1b2R (V)
-  ×1  
SPJ-1b2S (V)
-  ×1  
SPD-5b12 (G)



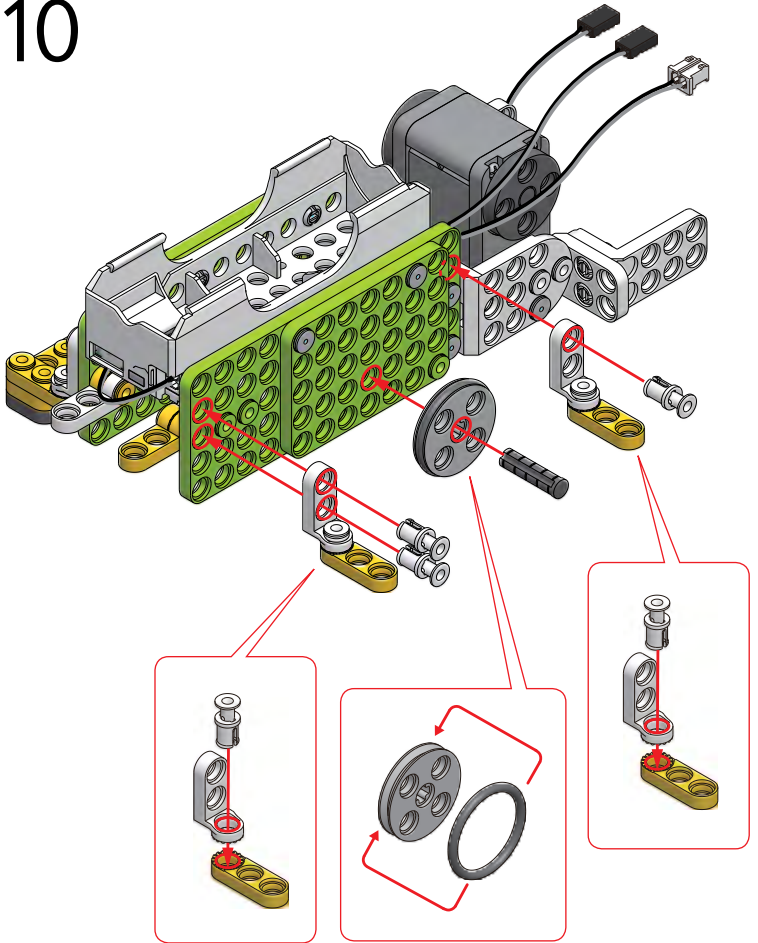




9



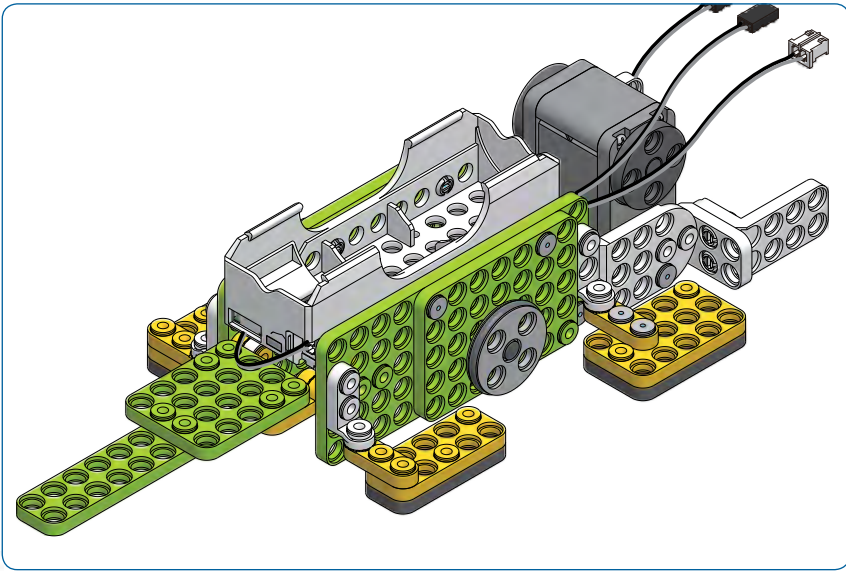
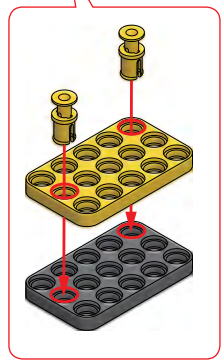
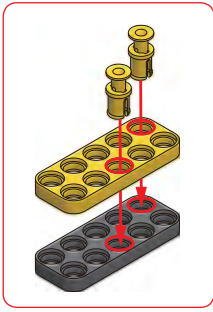
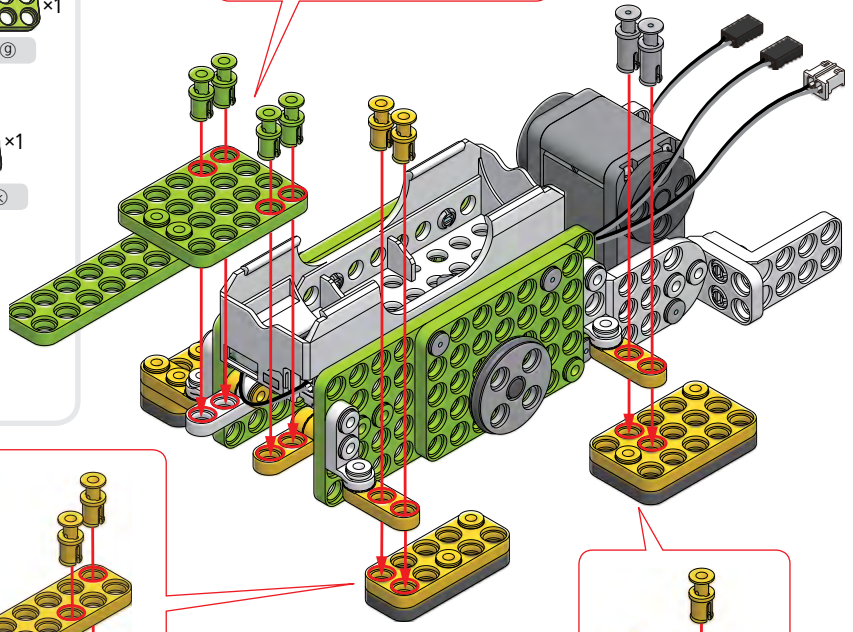
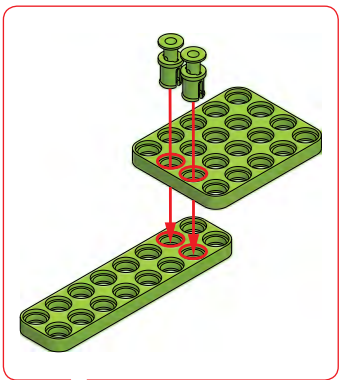
10





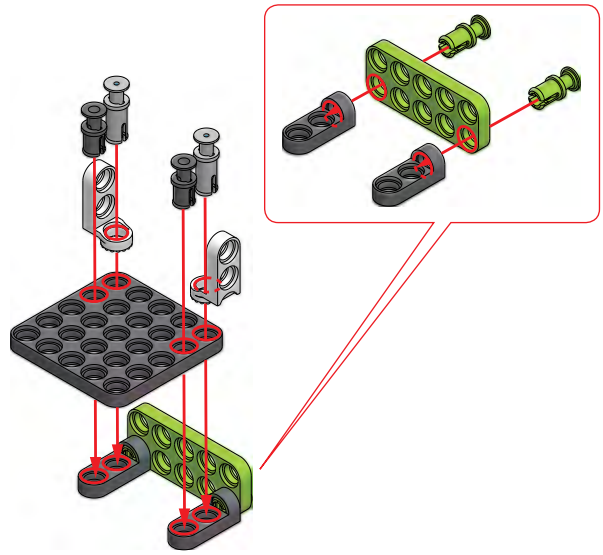
# 11

-  x6      x6  
 SRV-1H/1P Ⓞ     SRV-1H/1P Ⓞ
-  x2      x1  
 SRV-1LH/1LP     SPD-2b5 Ⓞ
-  x1      x1  
 SPD-2b5 Ⓚ     SPD-2b8 Ⓞ
-  x1      x1  
 SPD-3b5 Ⓞ     SPD-3b5 Ⓚ
-  x1  
 SPD-4b5 Ⓞ







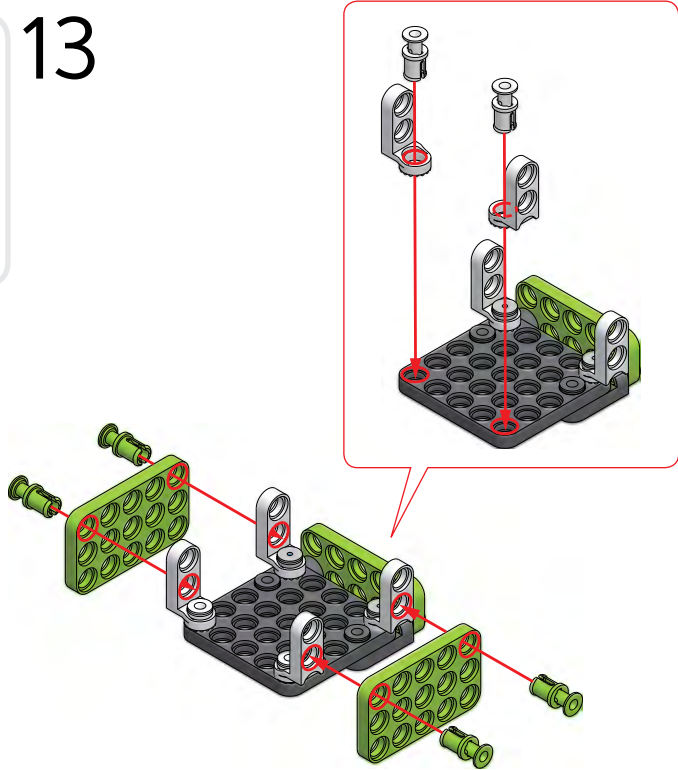
# 12

-  
- 
-  
-  



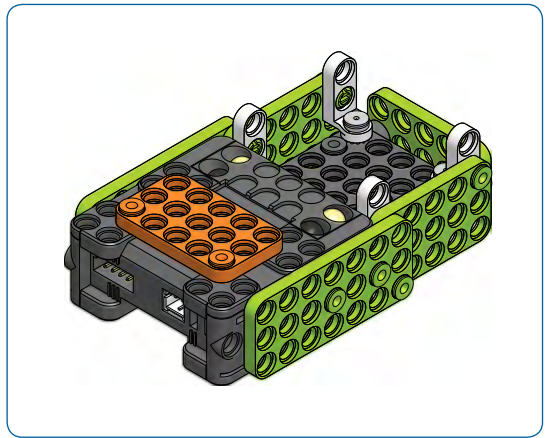
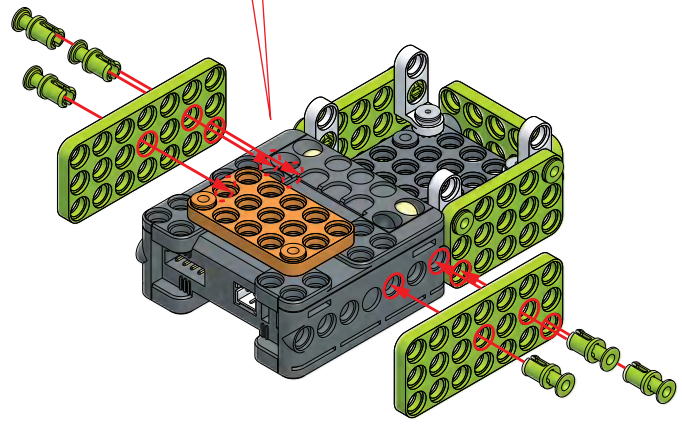
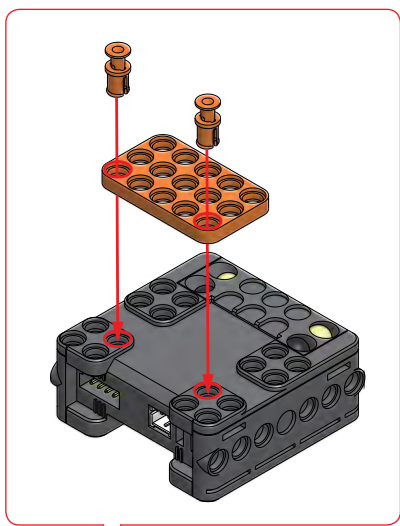
# 13

-  
-  

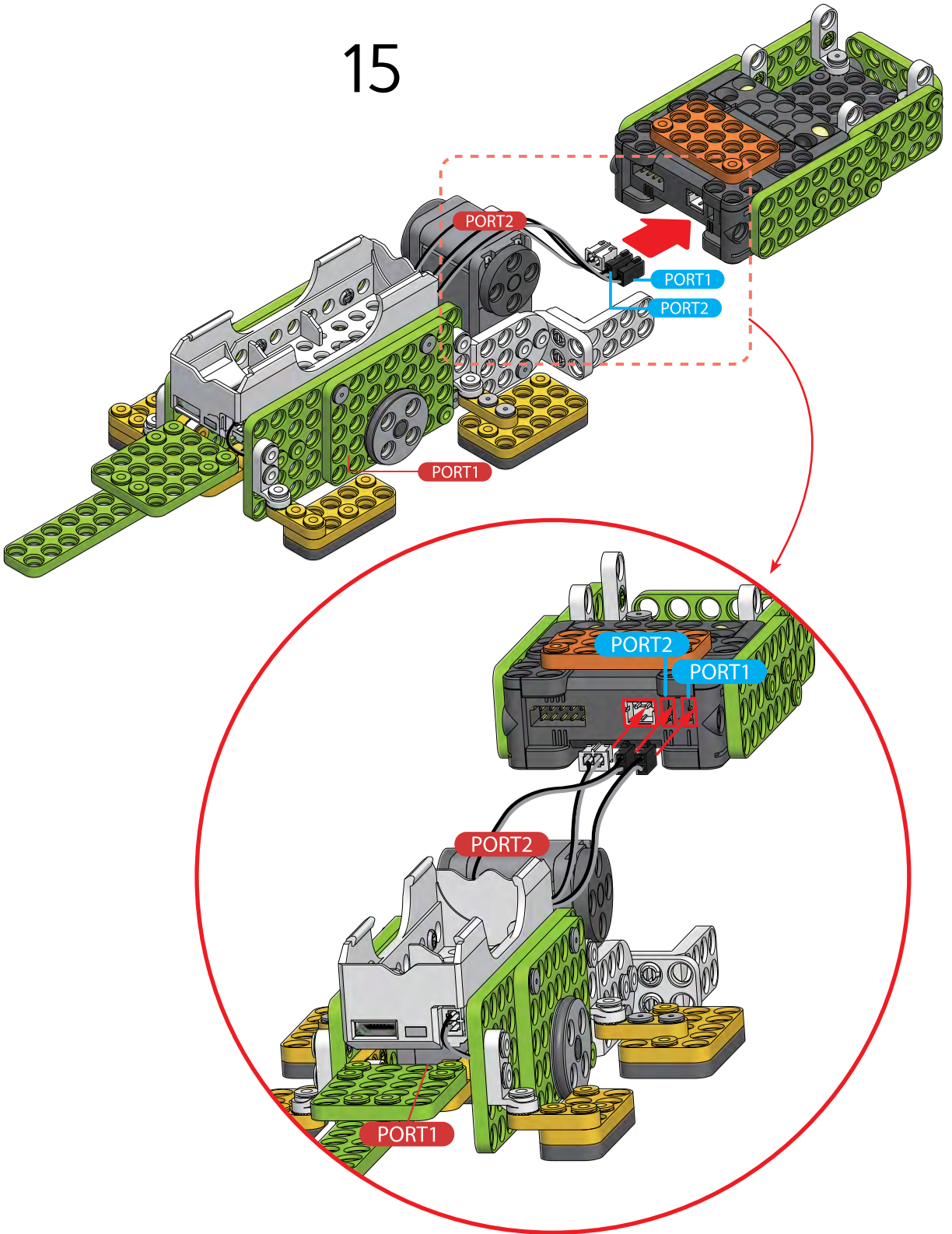


# 14

- SRV-1H/IP ⊙ x2
- SRV-1H/IP ⊙ x6
- SPD-3b5 ⊙ x1
- SPD-3b7 ⊙ x2
- CM-150 x1



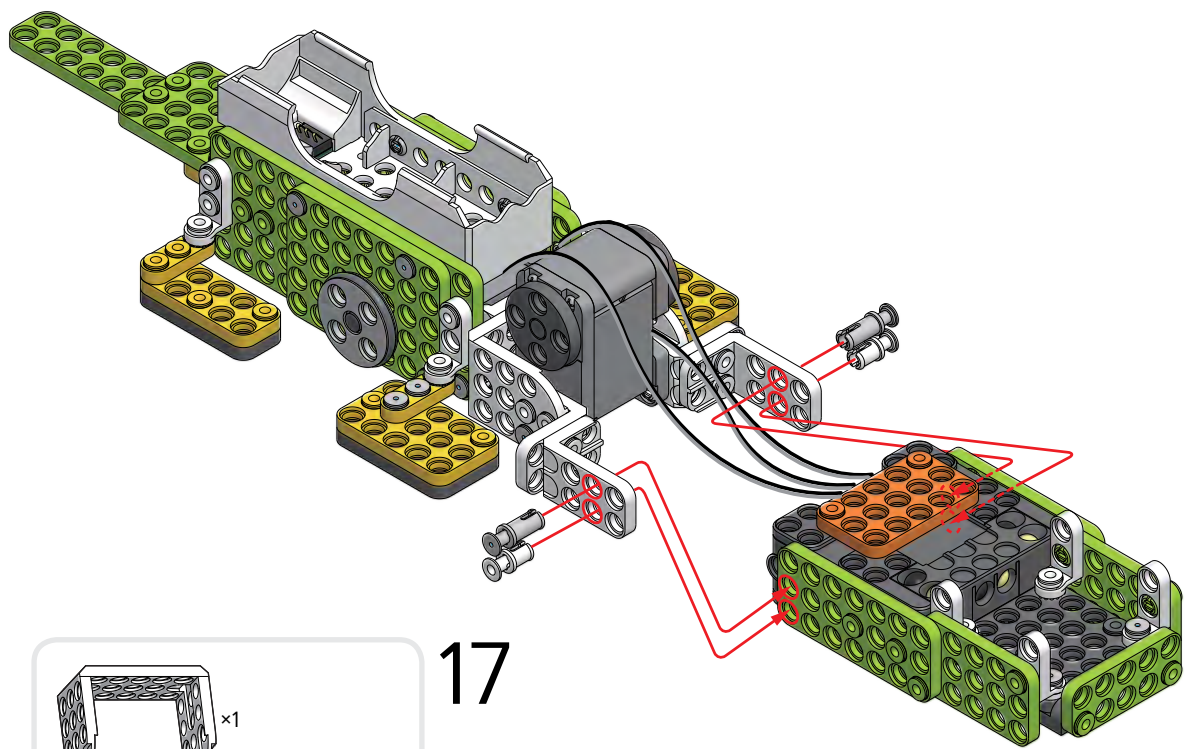
15





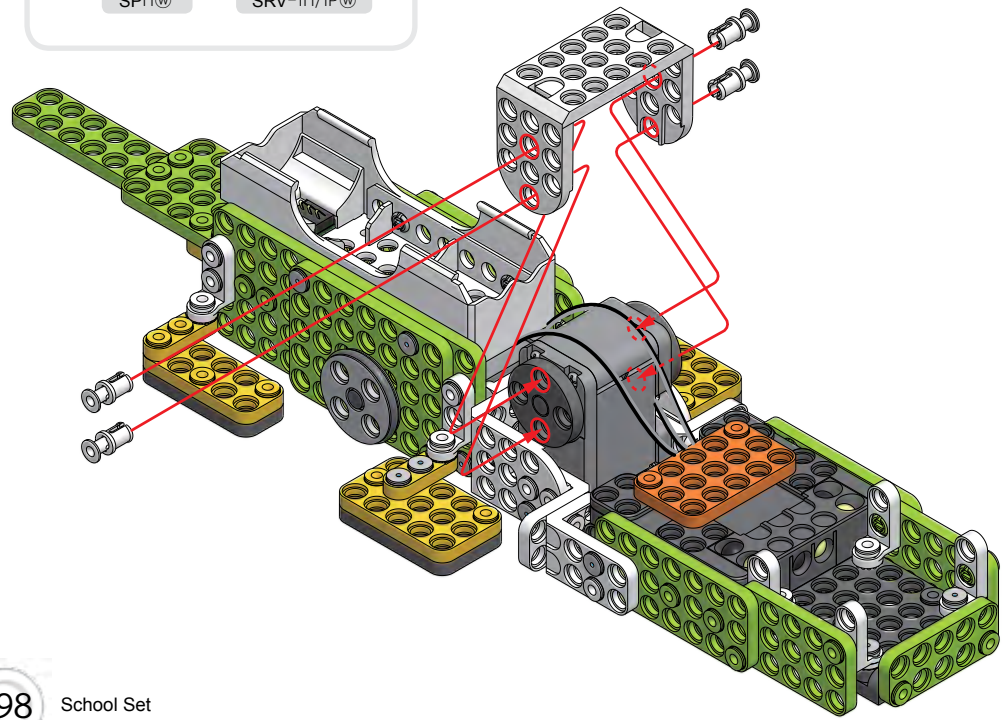
- SRV-1H/1PⓂ ×2
- SRV-1LH/1LP ×2

# 16

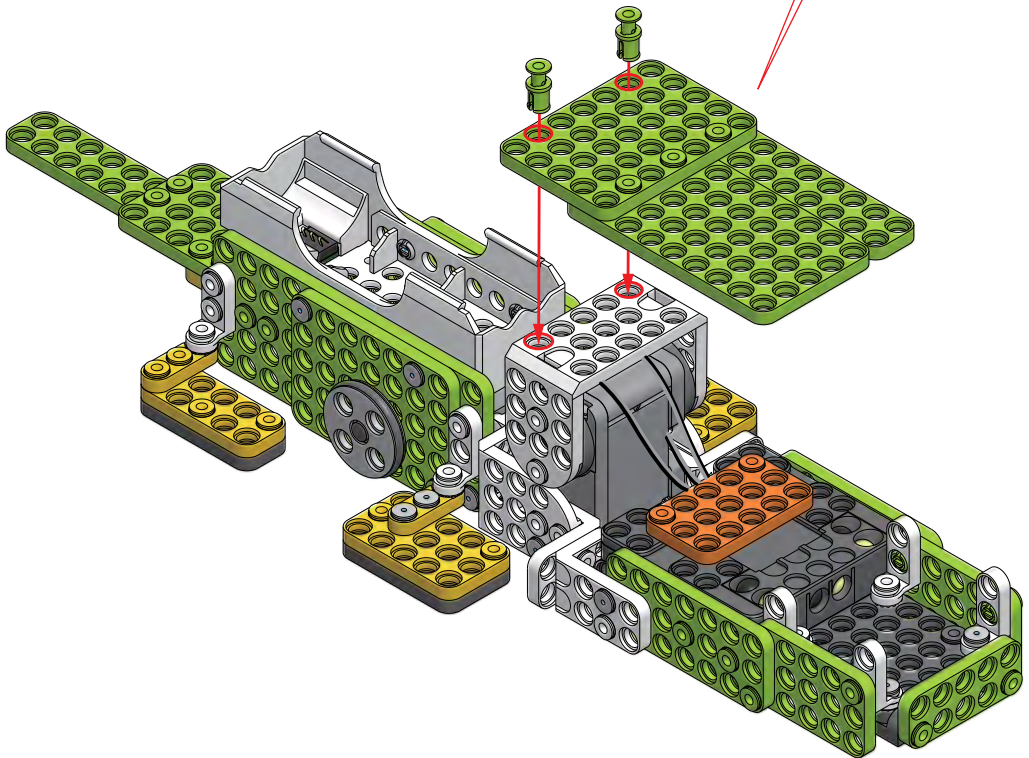
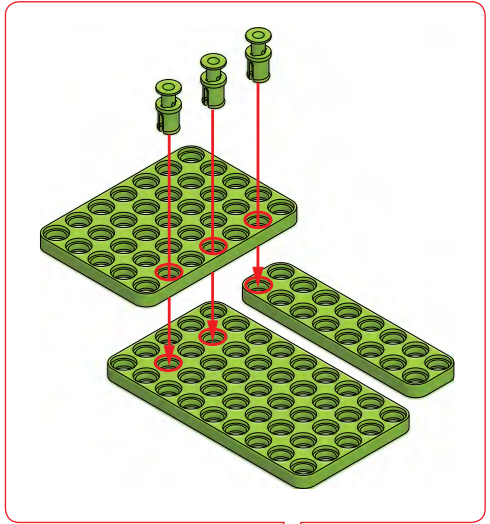
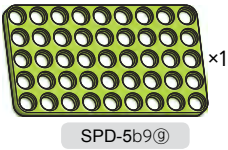
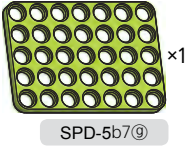


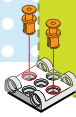
- SPHⓂ ×1
- SRV-1H/1PⓂ ×4

# 17




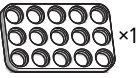

# 18

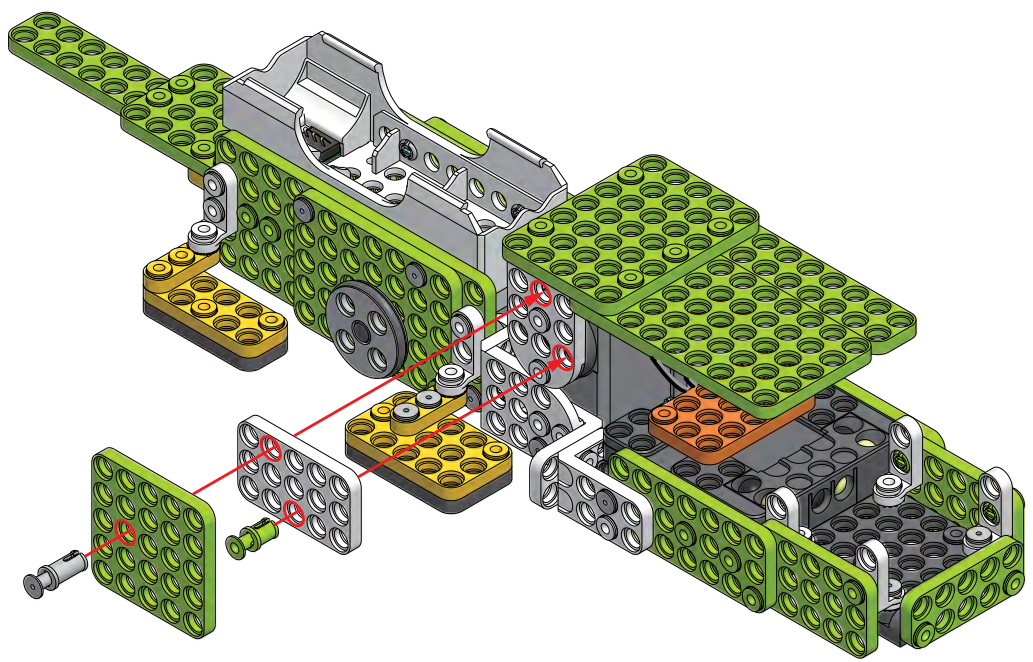




# 19

-  x1  
SRV-1H/1P
-  x1  
SRV-1LH/1LP

-  x1  
SPD-3b5
-  x1  
SPD-5b5





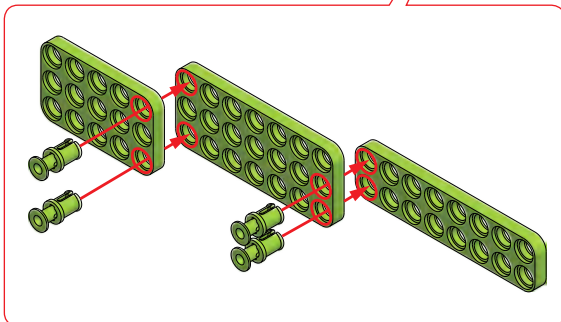
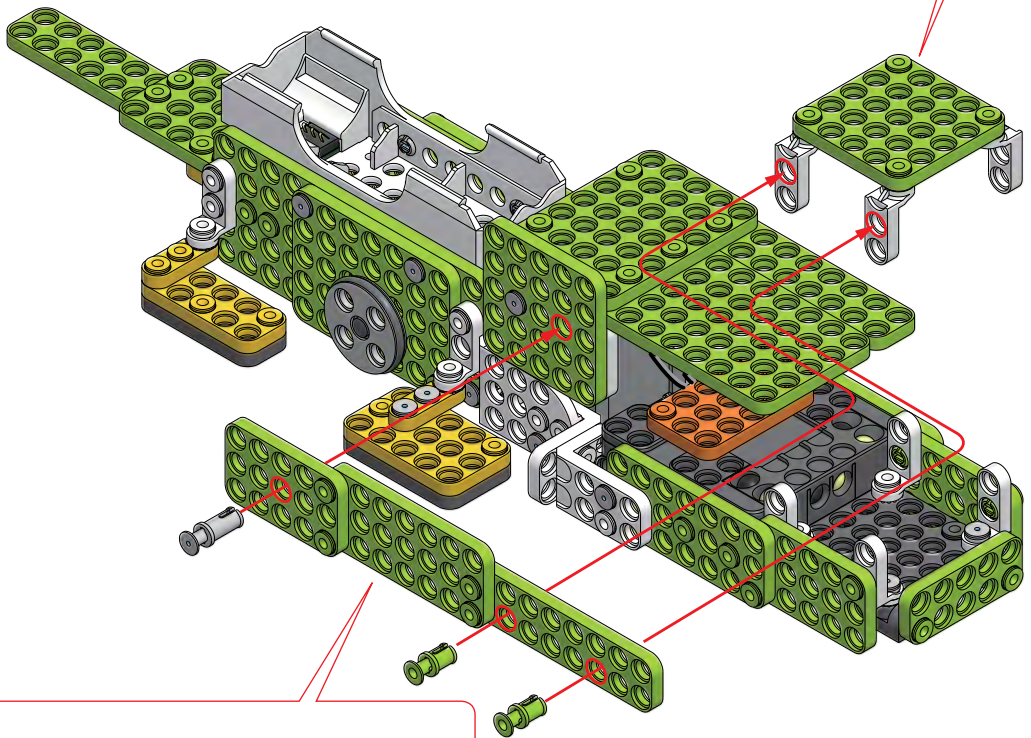
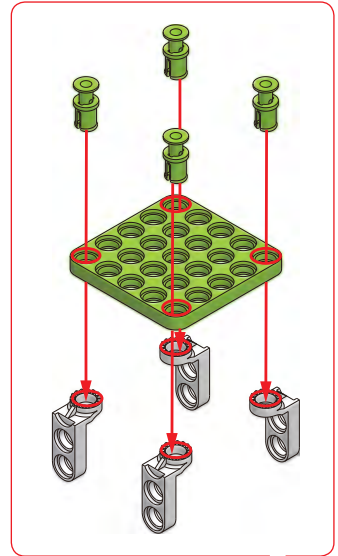
# 20

SRV-1H/1P  $\times 10$  SRV-1LH/1LP  $\times 1$

SPD-2b8  $\times 1$

SPD-3b5  $\times 1$  SPD-3b7  $\times 1$

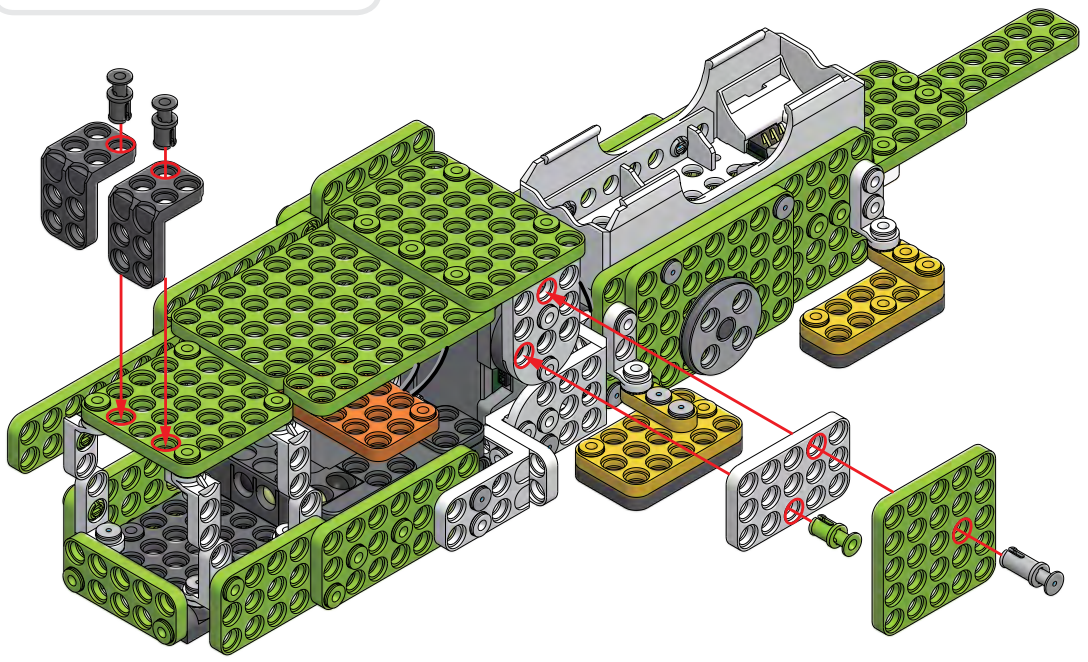
SPD-5b5  $\times 1$  SPJ-1b2P  $\times 4$





# 21

-  ×1  
SRV-1H/1PⓄ
-  ×2  
SRV-1H/1PⓄ
-  ×1  
SRV-1LH/1LP
-  ×2  
SPL-2b2Ⓞ
-  ×1  
SPD-3b5Ⓞ
-  ×1  
SPD-5b5Ⓞ



# 22

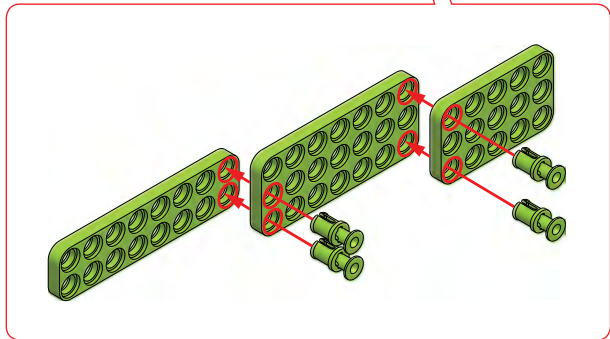
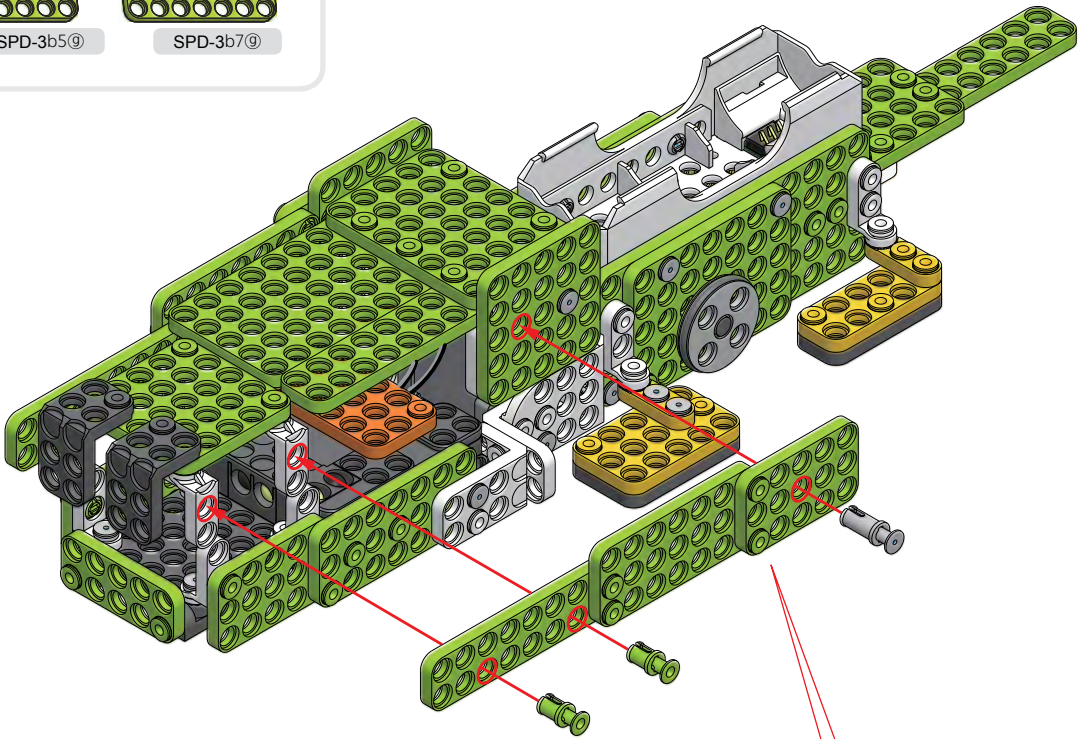
SRV-1H/1P ④ ×6

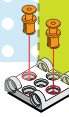
SRV-1LH/1LP ×1

SPD-2b8 ④ ×1

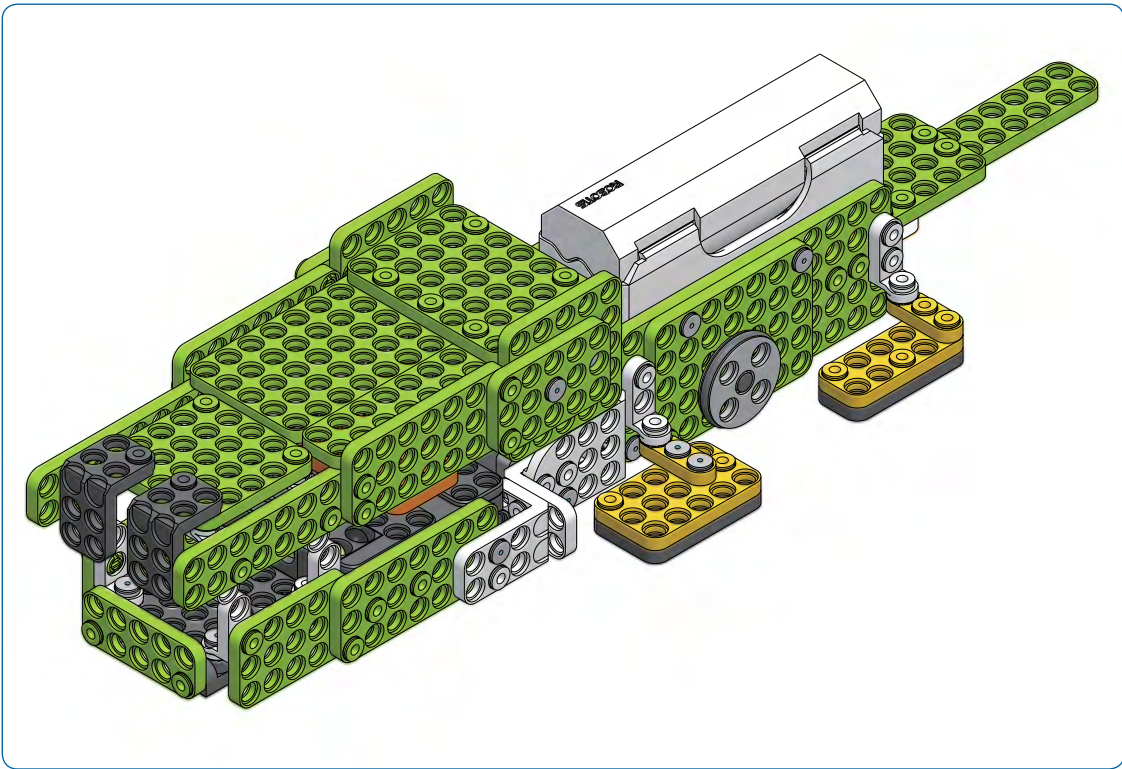
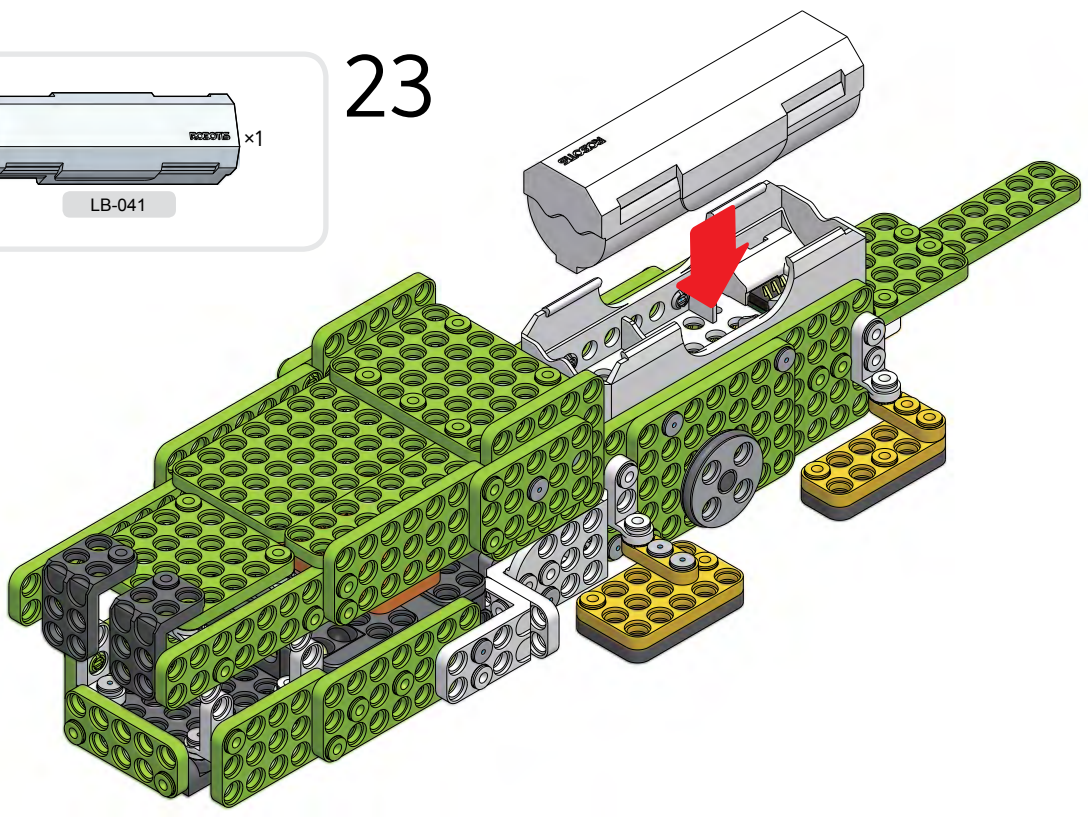
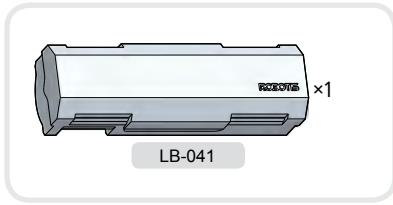
SPD-3b5 ④ ×1

SPD-3b7 ④ ×1

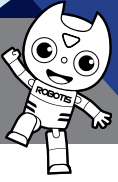




23





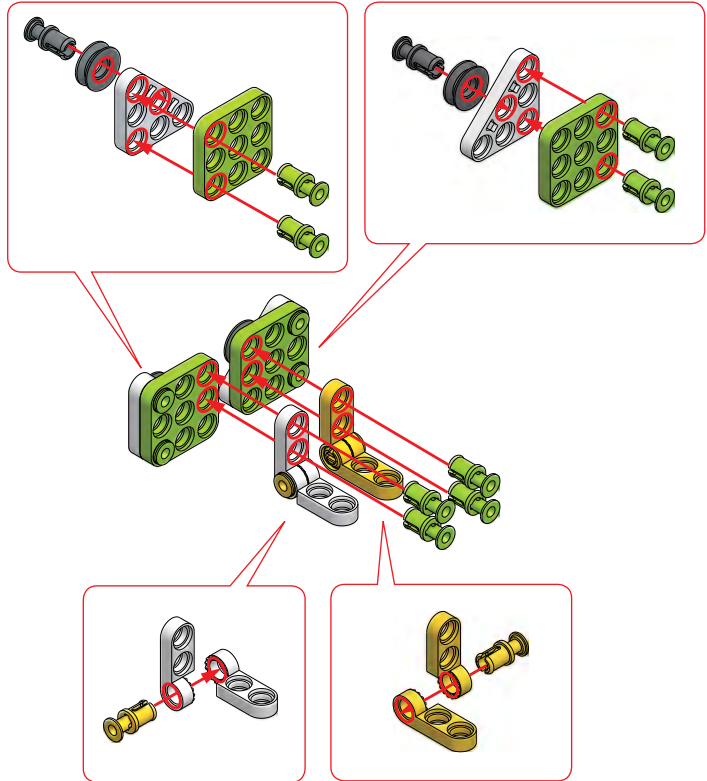


# My Own Robot!


Customize the appearance to make your own unique robot.

**1**

 x2	 x8
SRV-1H/1P(V)	SRV-1H/1P(G)
 x2	 x2
SRV-1H/1P(K)	SPO-1PR(K)
 x2	 x2
SPJ-1b2R(V)	SPJ-1b2L(W)
 x2	 x2
SPD-3b3(G)	p(SPA-3b3(W)



**2**

 x4
SRV-1LH/1LP

