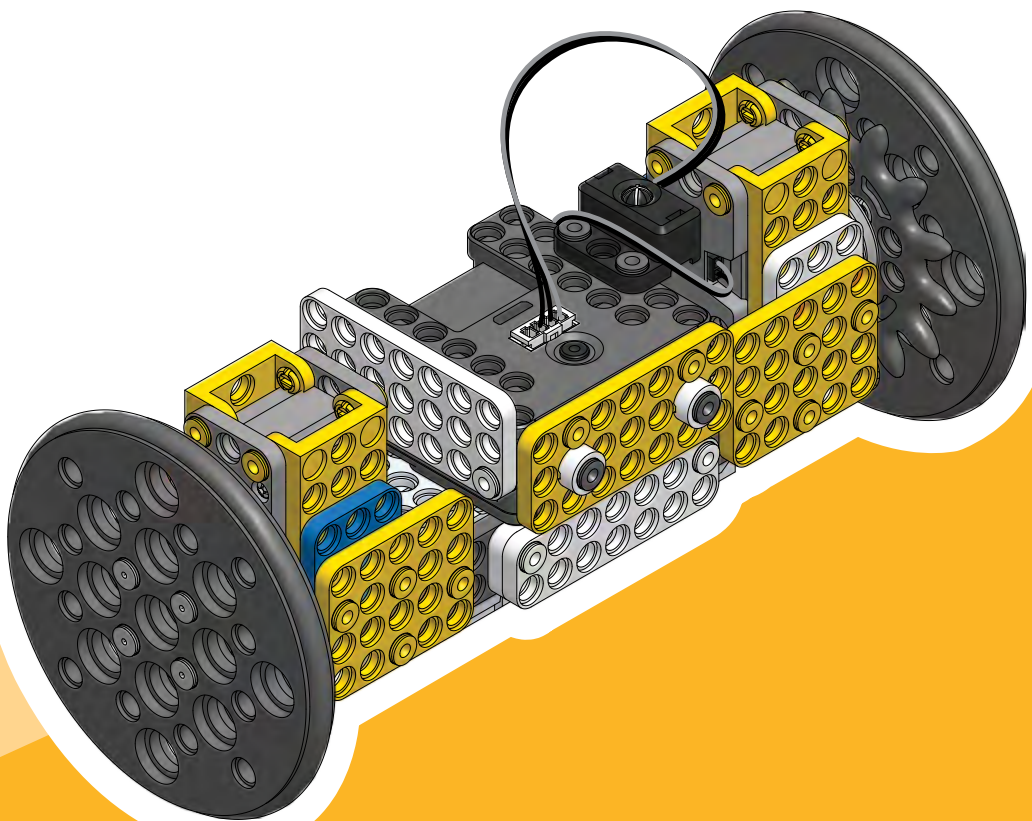


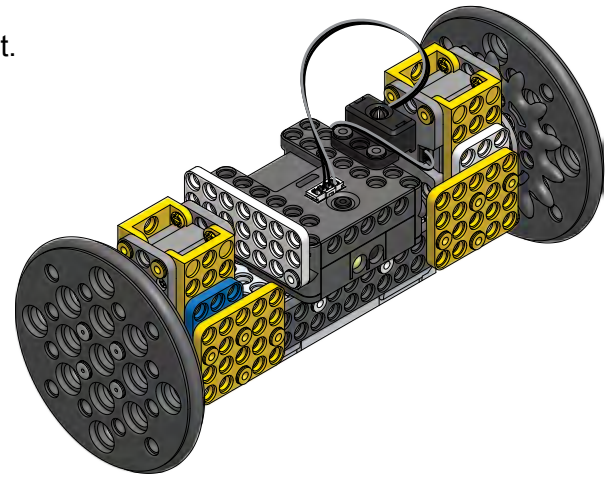


Roly Poly

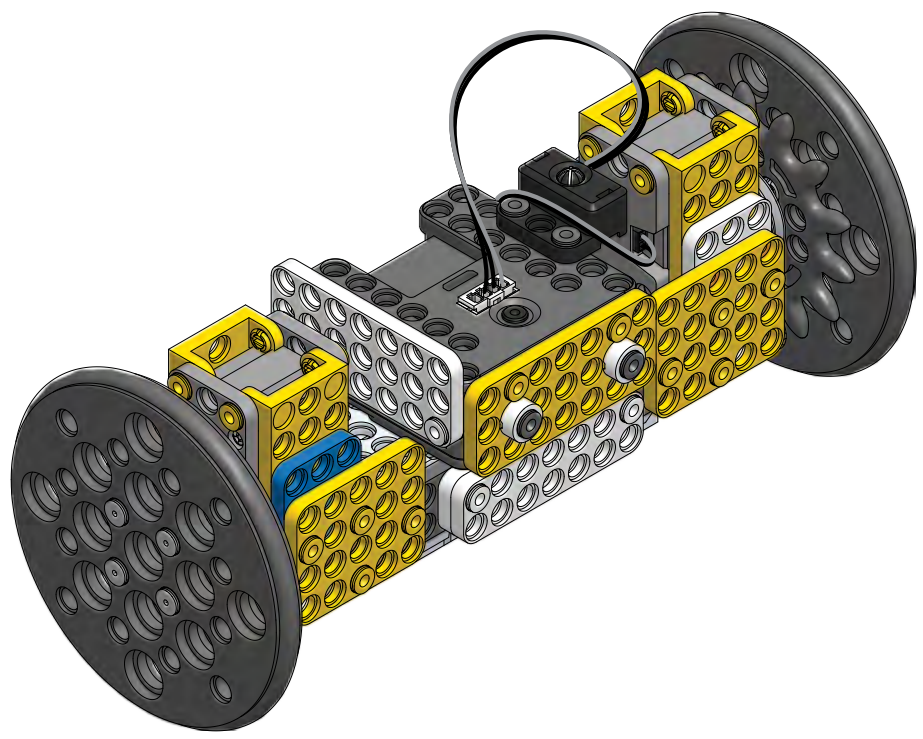


Let's build!

Let's build a robot.



Below is the final image of the robot when you are done with assembling the 'My Own Robot' step.

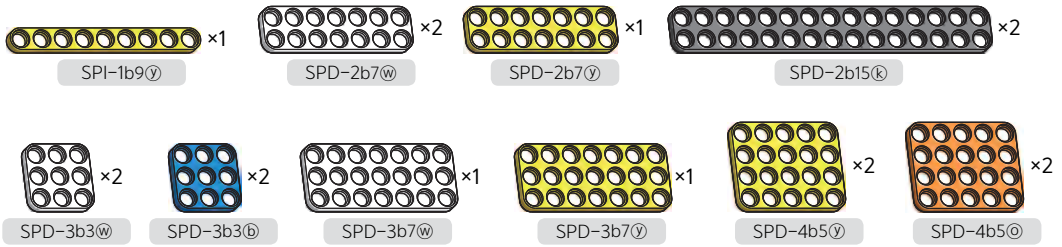


This chapter requires the following parts.

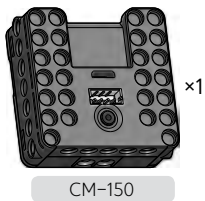
Rivet



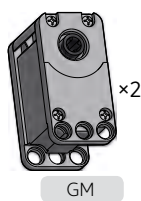
Plate



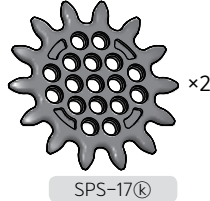
Controller



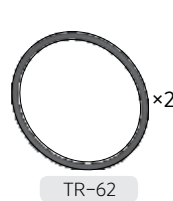
Geared motor



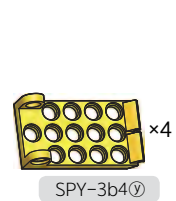
Sprocket



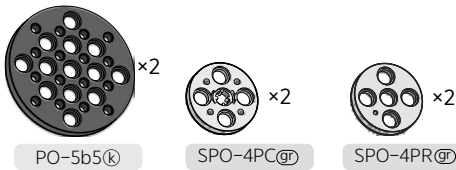
Tire



Adaptor



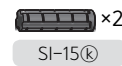
Pulley



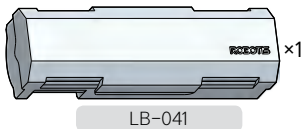
Spacer



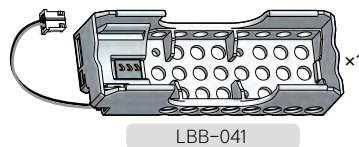
Spindle



Battery



Battery box





IR Receiver

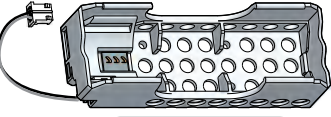


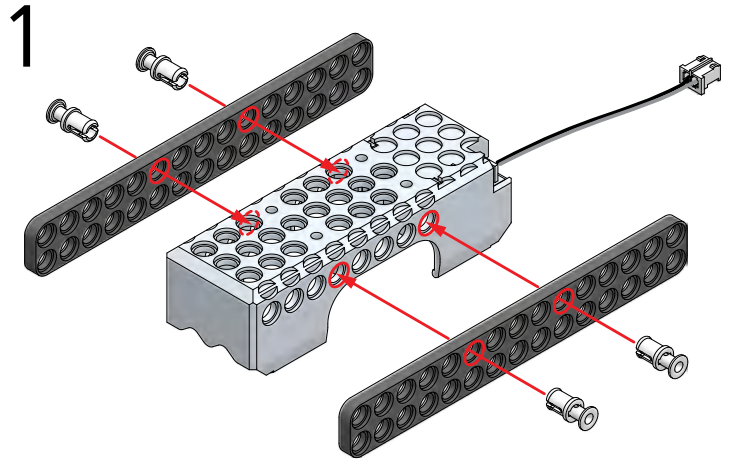
• Parts and color of the products might be different from the images of the assembly manual.


Building the roly poly


 x4
 SRV-1H/1P

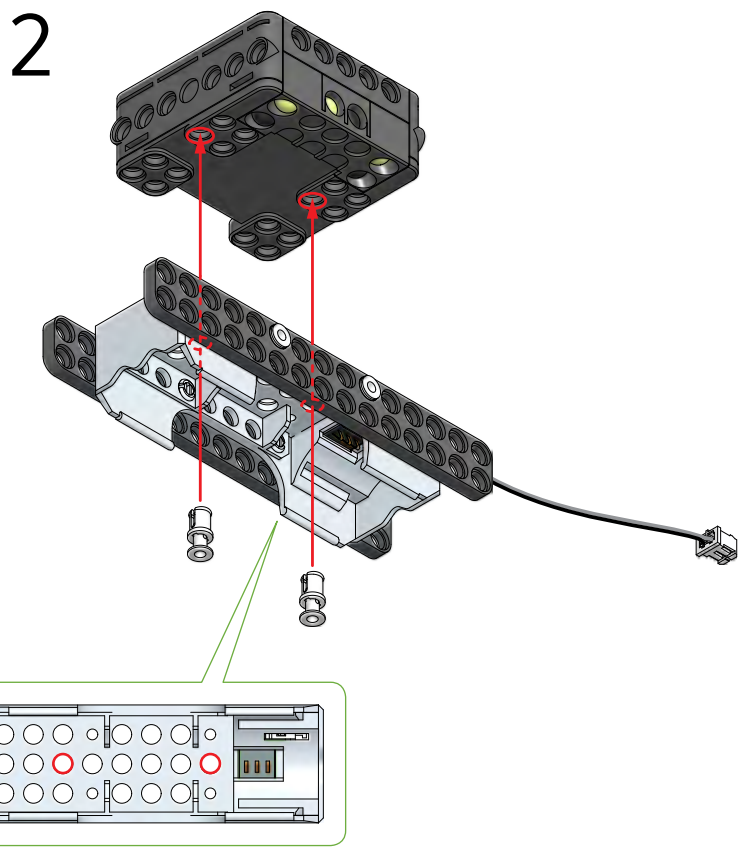
 x2
 SPD-2b15

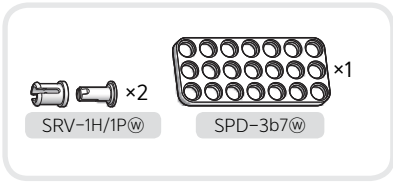
 x1
 LBB-041



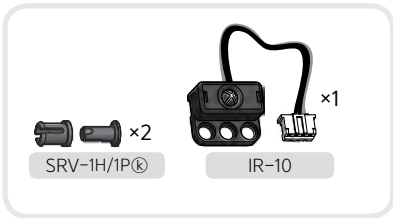
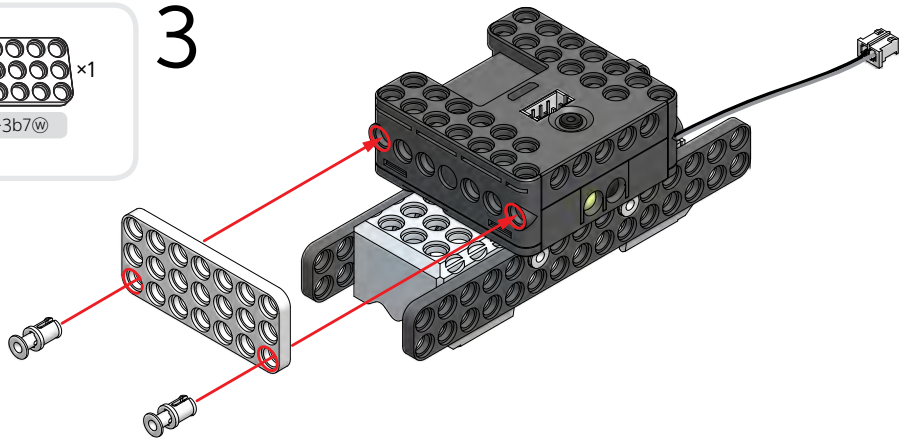
 x2
 SRV-1H/1P

 x1
 CM-150

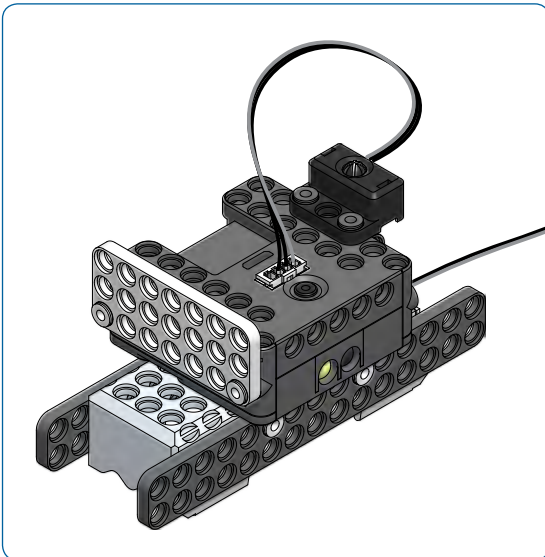
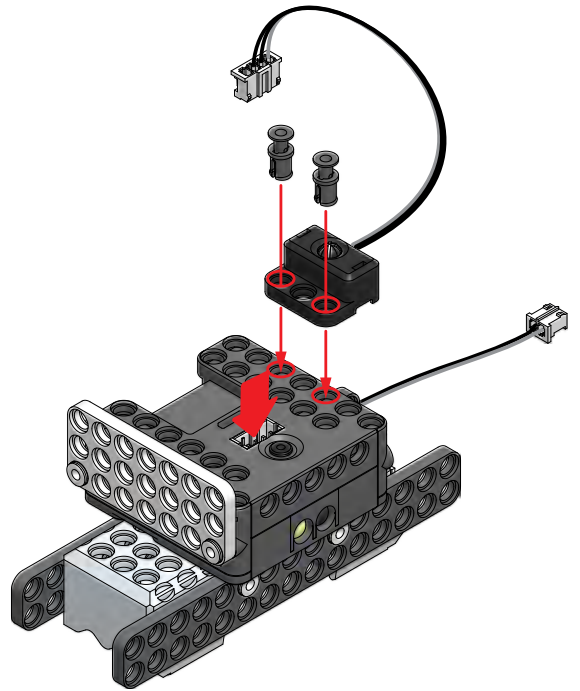



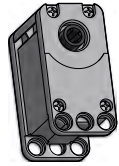



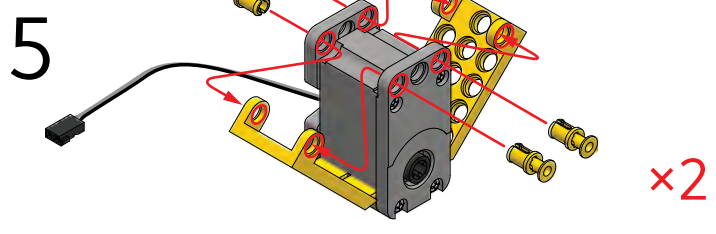
3




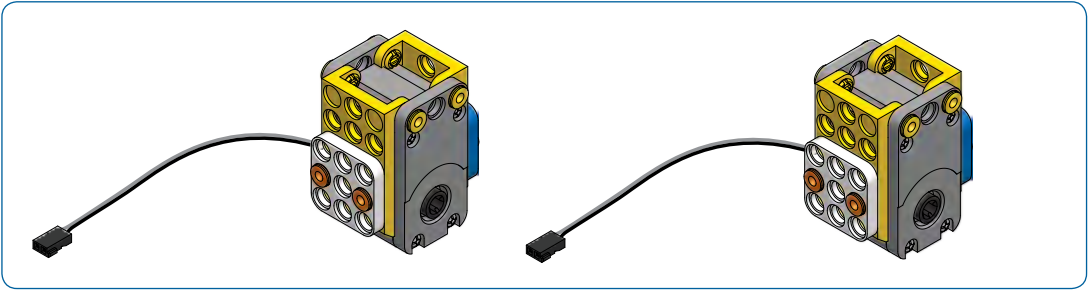
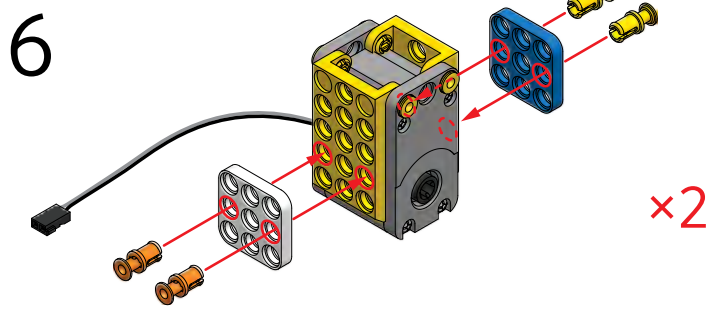
4





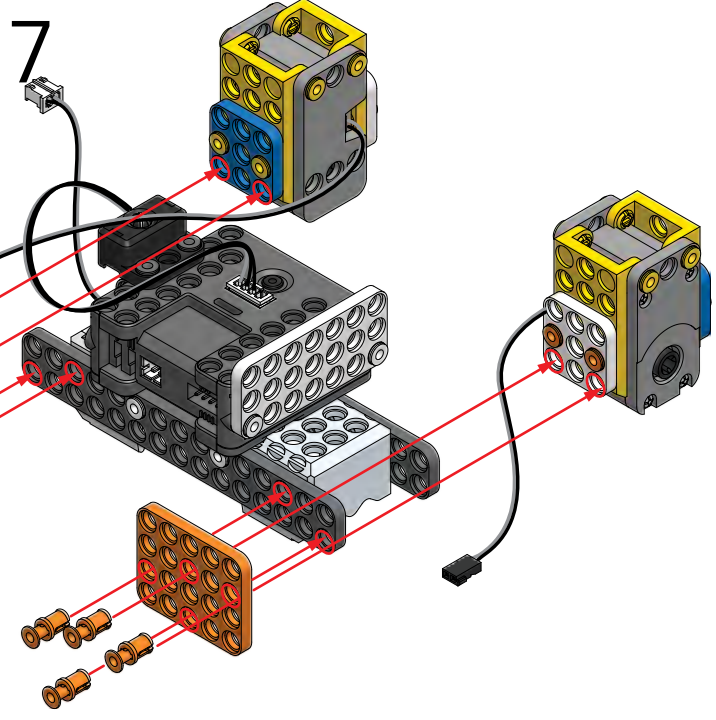
 ×8
 SRV-1H/1P  ×2
 ×4
 SPY-3b4

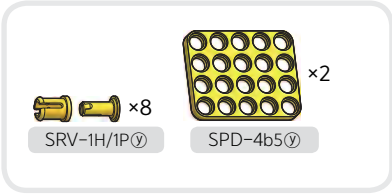


 ×4
 SRV-1H/1P  ×4
 SRV-1H/1P
 ×2
 SPD-3b3  ×2
 SPD-3b3

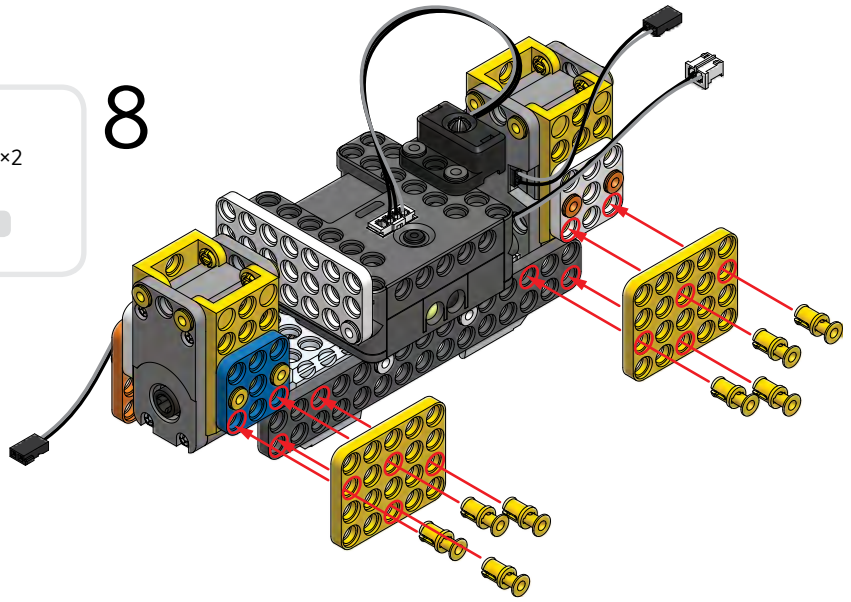


 ×8
 SRV-1H/1P  ×2
 SPD-4b5

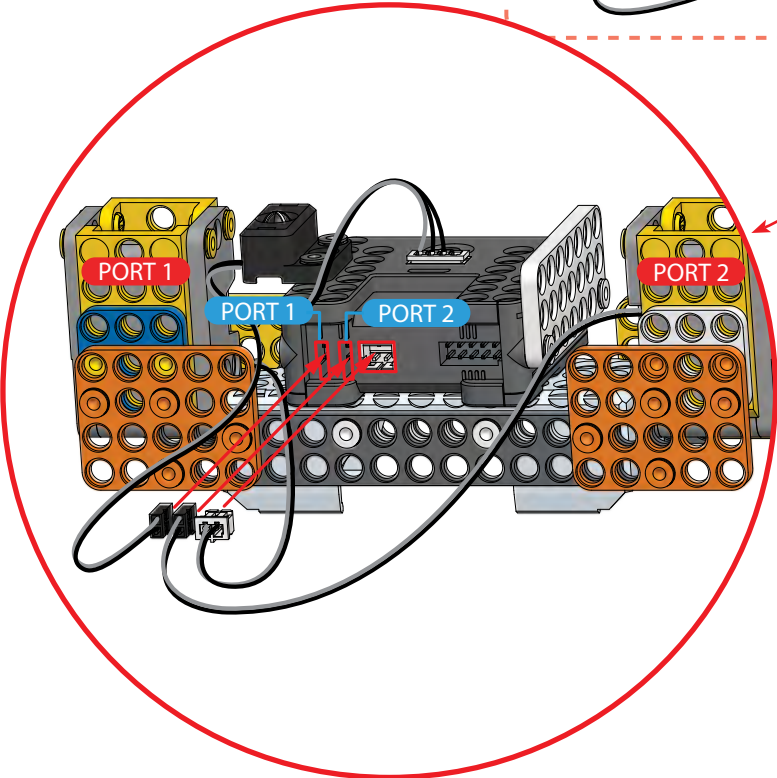
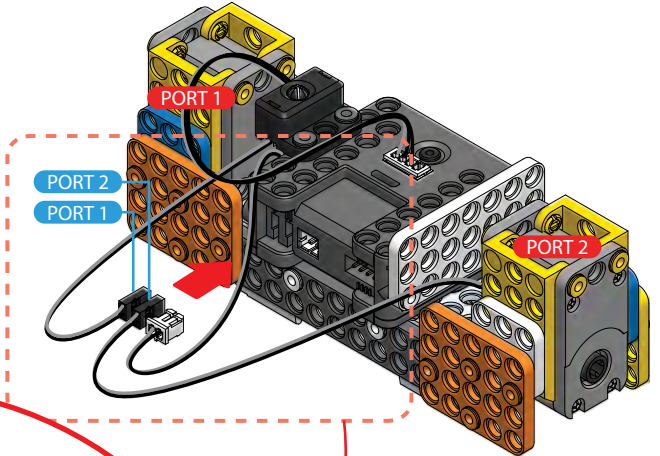






8

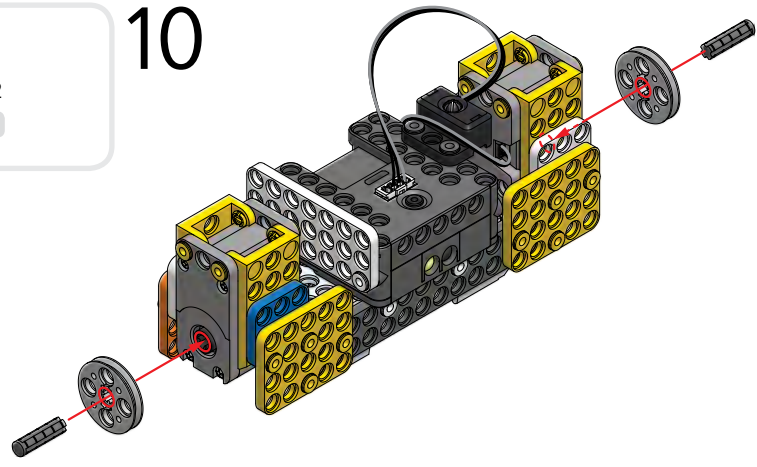


9



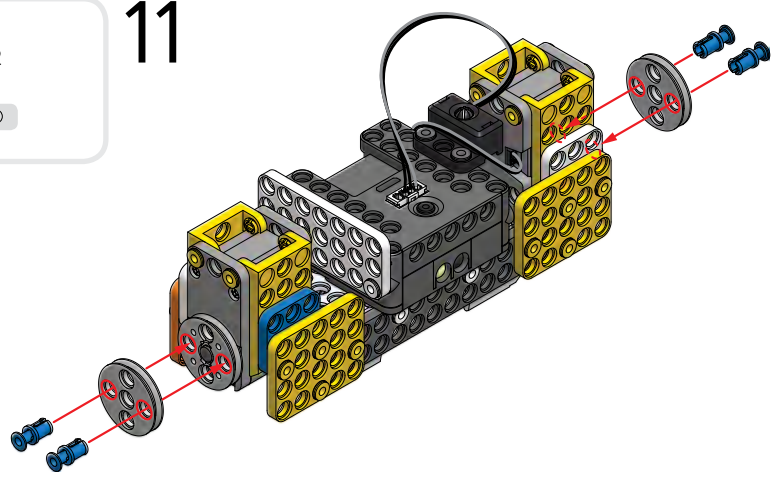
 ×2
 ×2
 SPO-4PC@
 SI-15(k)


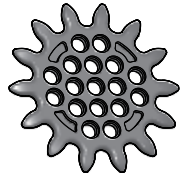
10



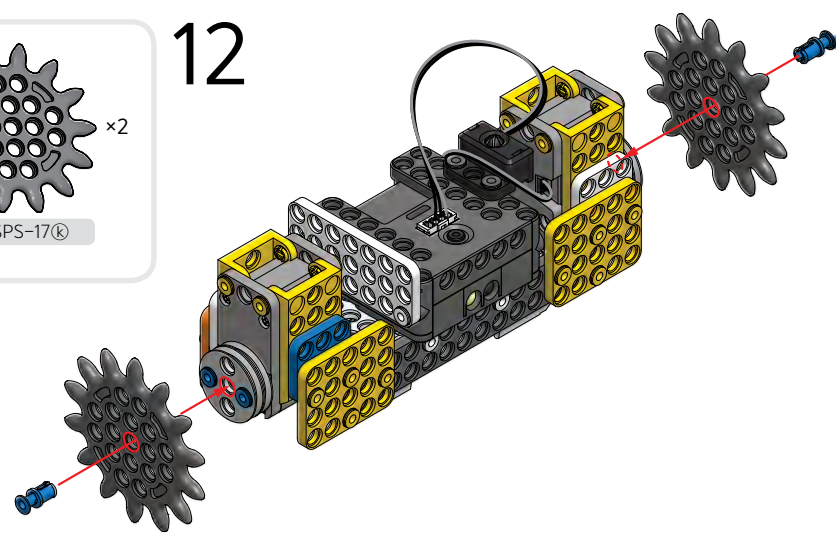
 ×4
 ×2
 SRV-1H/1P@
 SPO-4PR@

11

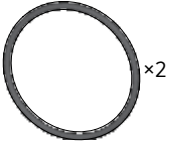


 ×2
 ×2
 SRV-1H/1P@
 SPS-17(k)

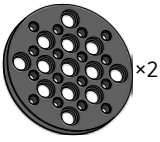
12



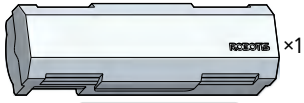
SRV-1LH/1LP ×8



TR-62

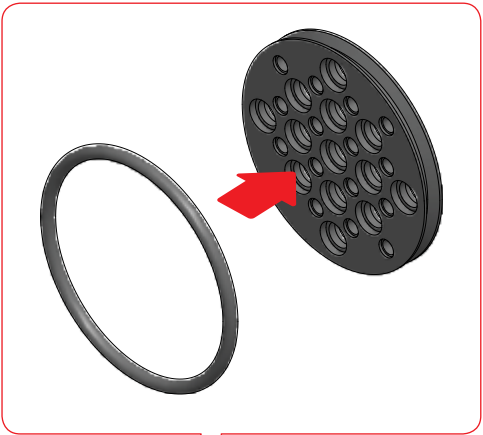


PO-5b5K

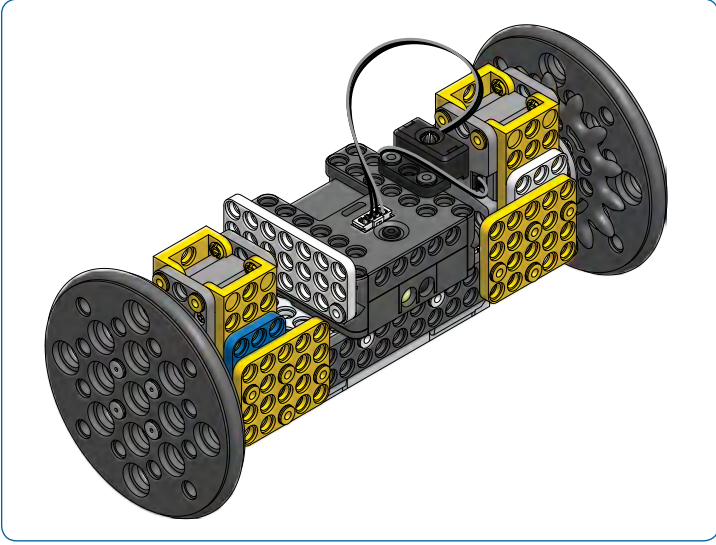
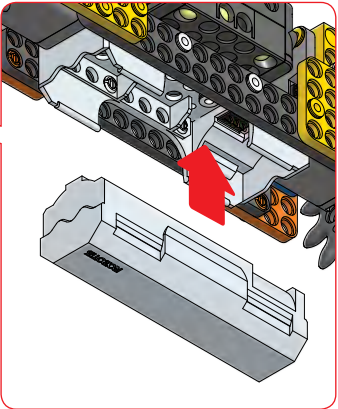
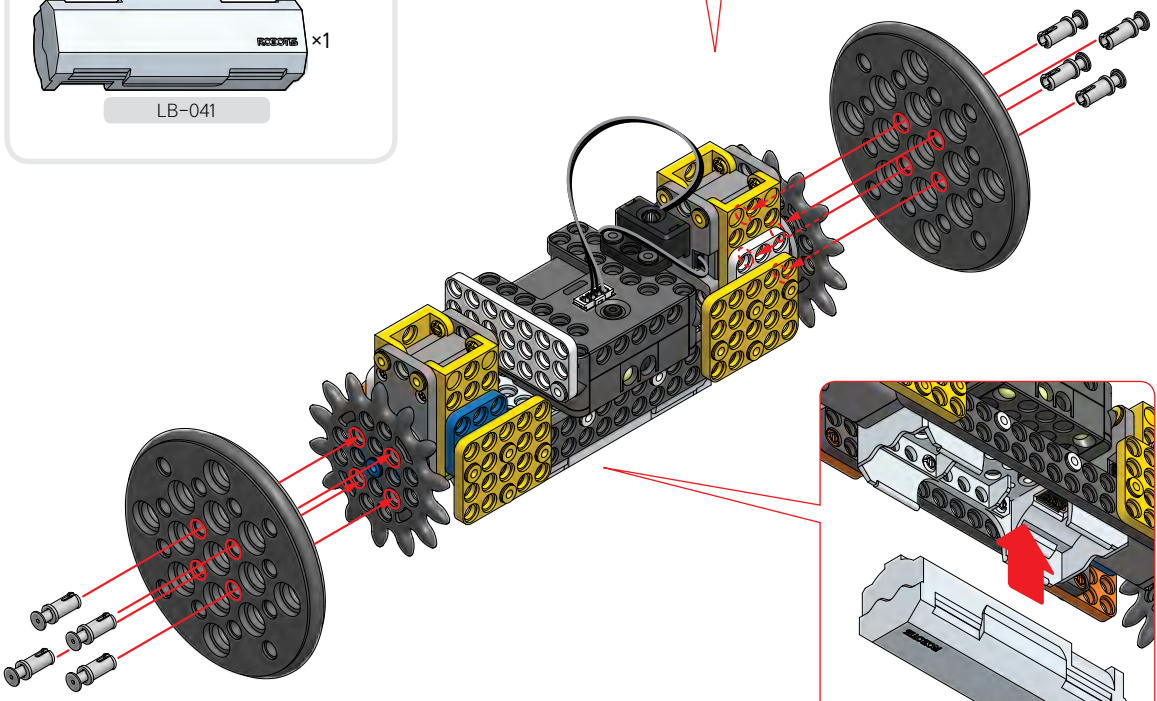


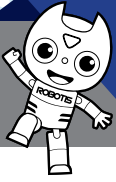
LB-041

13




×2






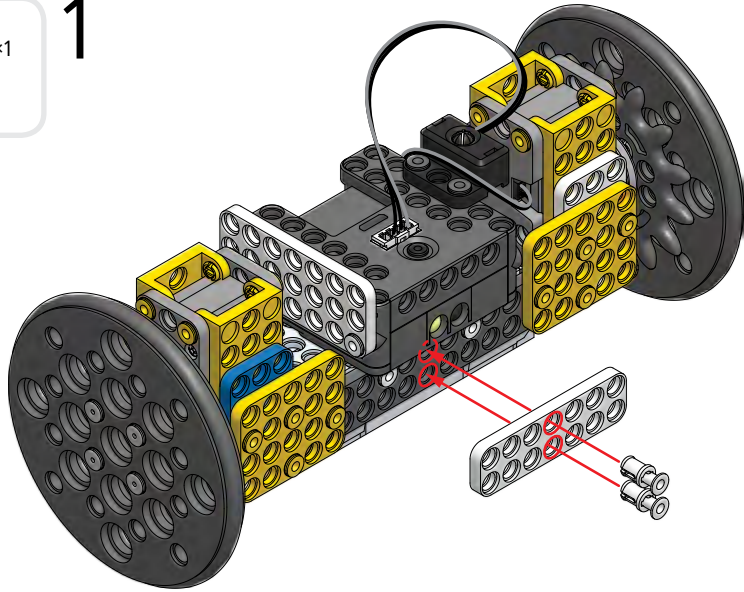
My Own Robot!


Customize the appearance to make your own unique robot.


 x2
SRV-1H/1P

 x1
SPD-2b7

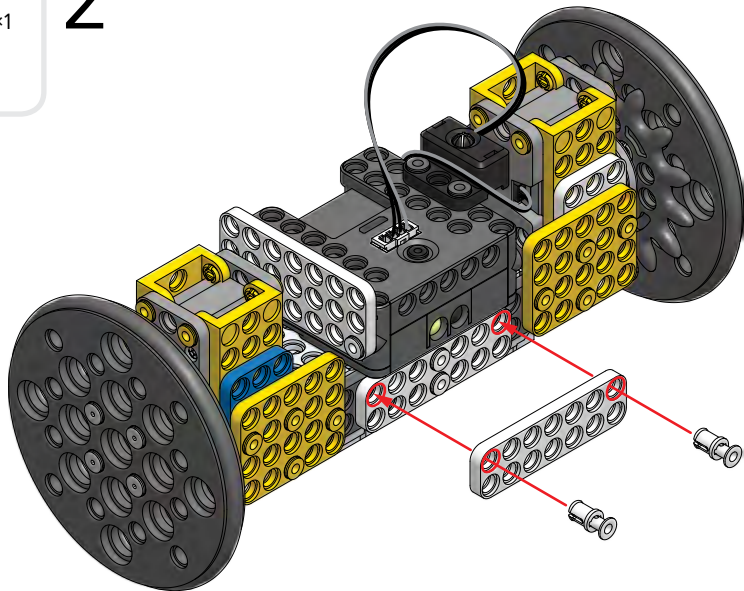
1







 x2
SRV-1H/1P

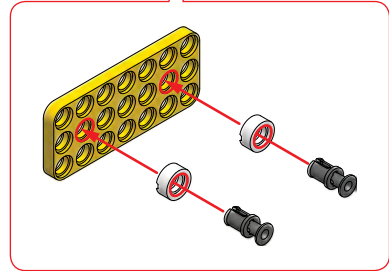
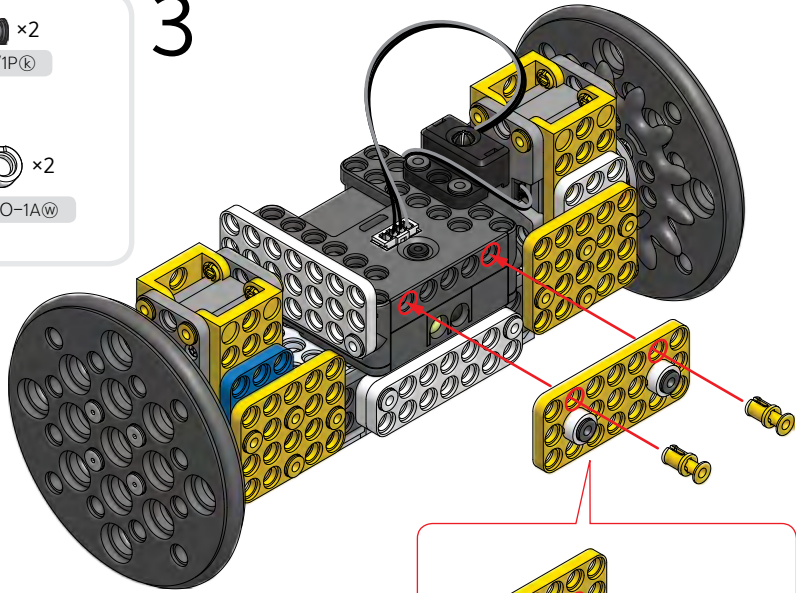
 x1
SPD-2b7





2



-  ×2
 SRV-1H/1P(γ)
-  ×2
 SRV-1H/1P(⊙)
-  ×1
 SPD-3b7(γ)
-  ×2
 SPO-1A(⊙)

3



-  ×2
 SRV-1H/1P(⊙)
-  ×2
 SRV-1H/1P(γ)
-  ×1
 SPD-2b7(γ)
-  ×1
 SPI-1b9(γ)

4

